

# **FiTROsway**

**OPERATING MANUAL** 

### I. CONNECTING THE STABILOGRAPHIC PLATE TO THE COMPUTER

The stabilographic plate connects to the computer by means of type A-B USB cable. Thereby, the system is ready for measurement.

### II. INSTALLATION AND RUNNING THE PROGRAM

FiTROsway program installation activates automatically after CD insertion, eventually by running the setup.exe file.



Click Next to start the installation.

🗟 FitroSway		
Select Installation Folder		
The installer will install FitroSway to the fi	ollowing folder.	
To install in this folder, click "Next". To in	stall to a different folder, enter it bel	ow or click "Browse".
Eolder: C:\FiTRONiC\		B <u>r</u> owse
,		Disk Cost
Install FitroSway for yourself, or for any	one who uses this computer.	
◯ Just <u>m</u> e		
	Cancel <back< td=""><td>Next&gt;</td></back<>	Next>

Installation program offers specification of directory to which the program should be installed. Default option is **C:\FiTRONiC** 

FiTRONiC diagnostic programs use a mutual database of measured subjects and the measured data are stored in the \Fitronic\Data\ folder. Therefore, when installing several programs, it is necessary to select the same folder for installation. It is not recommended to use Windows standard folder for installation of Program Files, because the active protection of Windows Vista and Windows7 does not allow storing user data in this folder.

To continue instalation, click Next.



To confirm instalation, click Next.

🛱 FitroSway			×
Installing FitroSway			).e
FitroSway is being installed.			
Please wait			
	Cancel	< <u>B</u> ack <u>N</u> ext≯	

Please wait a moment, until installation program copies the files. The installation of USB driver will follow.

Device Driver Installation Wizard				
	Welcome to the Device Driver Installation Wizard! This wizard helps you install the software drivers that some computers devices need in order to work.			
	< Zpět Další > Storno			

Click Next to continue.

Files of USB drivers have been copied.

Device Driver Installation Wizard	
The drivers are now installing	
b d	D
Please wait while the drivers install. This may take	some time to complete.
< Zpět	Další > Storno



Finish the USB drivers instalation by click on the "Close".

🕏 FitroSway			
Installation Complete			
FitroSway has been successfully installe	ed.		
Click "Close" to exit.			
	Cancel	< Back	Close

Click CLOSE to finish the installation procedure. To start the program click on the icon FiTROsway on the desktop (alternatively through start/programs/FiTRONiC/FiTROsway (double click on the icon).

### **III. RUNNING THE PROGRAM**

Starting the program opens the main menu on the screen.



One can run the program (e.g. to process the data stored on the harddisc) also without connecting the force plate, however, it is not possible to use **Test** routine and thus to perform the monitoring of COP movement.

### 1. FILE

### OPEN 🚔

Allows to load data stored on the disc for their further processing in a subprogram REPORT. By clicking **Load subject data**, a list of subjects, created through "Subject dialog" appears on the screen. File to be loaded is selected according to the date of measurement. If some data were stored outside of the default set folder for data, it is possible to open them after clicking **Load old data**. Data files use ending .swy.

Load Dialog	×
Subject selection	
·	
Load subject data	
Load old data	
Cancel	

### 1.2 SAVE F

Stores data from computer memory to disk. Should the name already on the disc be used, the system shows warning (OVERWRITE? Y/N). By confirmation the file overwrites the data from the previous measurements. Clicking "No" enables saving the file under a different name.

### 1.3 OPEN CFG 불

Opens the configuration file with setup parameters of the program.

### 1.4 SAVE CFG 📕

Saves the settings of the parameters and conditions to the configuration file.

1.5 PRINT 🎒

Prints the current window with data from the measurement.

### 1.6 PRINT PREWIEW

Preview before printing - previews the data on the paper before printing.

### 1.7 EXIT

Closes the program.

### 2. SUBJECT INFORMATION 🕱

Input of information about a person tested: given name, family name, date of birth, sex, height and weight. There is also a window for your own comment. The information will be stored in the same file with test data into a corresponding folder.

Subject Dial	og	×
Given name Family name Birth	John       Black       Day     Month       18     07	
Club	Slovan Bratislava	
Weight (kg)	Add club	
Height (cm)	188	
Comment		
Search for subject	Pick up selected	
ОК	Cancel	

For an easier orientation in the data, a hierarchic arrangement of the data is suggested in FitRONic programs. At inserting new subject information, the following items are mandatory: Given name, Family name and Birth Year. These entries are used when creating a folder for the tested person. In the example above, a folder Black John 1990 is created. Next subfolders will be consequently created in this folder for FiTRONiC product applications. In particular subfolders e.g. GATES, AGILITY, JUMPER, PREMIUM etc., a subfolder YYYY MM DD will be created according to the date for each testing day, where all files for a given subject measured that day will be stored. In case there are already some data recorded for a given subject, it is necessary to search for it through Search for subject window and select it into the displayed dialog by clicking **Pick up selected** so you can retrieve once inserted data for any application. A list of clubs is created as well in the main data folder which can be extended in the Adding club into directory window. By inserting the club name and subsequent adding through the Add club button, the club name is added into the list of clubs and can be found and selected again for a corresponding subject in the Club window. In the ...\FiTRONiC\DATA\ folder, a clubs.xml file is created, which can be edited when needed.

After data insertion one can return to the main menu by clicking OK. Subject information data can be added later - after measurement before saving the data.

### 3. TEST



Routine for monitoring the movement of the COP (center of pressure) during quiet stance. Window will appear to enter the time interval for the registration and storage of the data.

	×
Saving Time (s)	
1	
,	
OK	Cancel

Click OK to run the monitoring of current COP position. In the left pane of the screen the current COP position is displayed in the horizontal plane (axis X,Y). In the right pane the current coordinates X and Y are displayed.



Button **Center** serves to centre the COP point into the middle of the chart, click **Start** to start data recording - lines COP-X and COP-Y change color and time data appears on X axis. After the set time interval elapses, system continues to monitor COP. Click **Start** for recording another trial period, or click **Exit** to end the measurement routine.

# 3.2 CONTINUE STANCE TEST WITH SAME SUBJECT

Continues the measurement routine with the same subject. Data from test to follow will be added to those from previous tests (or loaded to computer memory from disc).

## 3.3 TARGET HITING TEST

Serves for measurement of the times the subject needs to hit the targets randomly appearing on the screen by shifting his/her COP. Also distance covered by COP from the moment of target appearance to its hit is recorded.

Before the test, the number of targets to be hit is set. Also the kind of target generation (random or programmed) can be specified.

To use "program generation" one has to create and save protocol beforehand. Before the test the protocol must be loaded in a routine "OPEN PROTOCOL".

Target Hiting Setup 🛛 🔀			
Custom     Number of stimuli to follow: 10			
C Protocol Protocol name: no protocol loaded Load protocol			
OK Cancel			

By clicking OK, a monitoring window opens in which the COP movement is displayed. Click on the **Center** button, shifts the COP to the middle of the screen. By clicking **Start**, targets are generated.



After the test, a report appears showing the stimulus order, movement direction, distance covered by COP, response time and COP movement velocity.

FiTRONIC - Fit	roSway				
	* <b>X X</b> X X	.). a 🖡 🗐 🗧 🗐	12, ž. ž. ži 🛩		<b>3</b> 9
	Copy Copy All	Export xml Dele	te		
Name: Slovak Ja	an		w	eight: 80	
	1				
No	Movement	Distance	Time	Velocity	
(#)	Direction	(m)	(ms)	(m/s)	
1	right	0,263	10080	0,026	
2	rear	0,081	900	0,090	
3	right	0,069	940	0,073	
4	front	0,070	960	0,073	
5	rear	0,095	1010	0,094	
6	front	0,104	1040	0,100	
7	right	0,094	1200	0,078	
8	left	0,088	1100	0,080	
9	front	0,108	1600	0,067	
10	left	0,189	2870	0,066	
Average:	mean value & SD	0,116 SD:0,059	2170 SD: 2690	0,075 SD:0,019	

## 3.4 DRIVING TEST

Test assesses the ability to control the COP position based on visual feedback. The role of the person tested is to stay as close as possible to the line "floating" on the screen in vertical or horizontal direction.

After activation of the routine, window with test parameters appears. Duration of the test is set in the **Test time** window. The choice **End with button Stop** allows you to end the test by clicking Stop which is being displayed on the screen during the test. In other parts of the window it is possible to set the direction and velocity of the generated curve.

Driving Setup end with time end with button stop Test time (s) 10	Driving test - Direction C UP - DOWN DOWN - UP C LEFT - RIGHT RIGHT - LEFT	Driving velocity
	Cancel	OK

By clicking OK, a monitoring window opens in which the COP movement is displayed, by the Center button, the COP graphically moves to the middle. By clicking Start, the curve is generated.



A digital report appears after the test:

	FiTRONiC - FitroSway	×
File	ile Subject Exercise View SetuP About	
	🖆 🖬 🔓 🗃 🎒 🏋 🤾 🥇 🌾 🤾 🚷 🐟 🔻 🕹 💈 🤹 💈 🖉 🖉	
	Name: Slovak Jan Weight: 80	
A	Average distance: 16,4 SD: 25,0	
A	Average distance squared: 372,2 SD:468,4	

Average distance (mean and standard deviation) of the COP from the curve. Average distance squared (mean and standard deviation) of the COP from the curve.

## 3.5 CONTINUE DRIVING TEST WITH SAME SUBJECT

This is used for starting a measurement with the same subject, if we have data from a previous measurement or from an open file in memory. New measured data will be added to the previous, i.e. if there are 3 trials measured, trial no. 4 will follow.

## 3.6 CHECK 🍄

Displays readings of the load on the individual force plate force sensors. If there is not a zero value in the **SUM** window when the plate is unloaded, click **ZERO to** set it to zero. The value is saved to the configuration file. It is not necessary to carry out such control and zeroing before each measurement. On the other hand, it is advisable to check the percentages of the load on the individual corners of the plate on which a tested person is standing. The values of the load should not exceed 90 % for the risk of exceeding the measured range and distortion of the results. It is necessary to "relieve" the overloaded tensiometer by shifting the stance away from the overloaded corner.

	FRONT LEFT		FRONT RIGH	т
(#)	116		123	(#)
(%)	2,85		3,01	(%)
		0104		
	×(mm)	SUM	Y(mm)	
	0,0	0	0,0	
(#)	122		112	(#)
(%)	3,00		2,75	(%)
	REAR LEFT		REAR RIGHT	

#### 4. VIEW

4.1 Real Simulation



Simulates the measurement - starting the movement of the curves. Click on the buttons above the charts movement of the curve can be specified (fast rewind, normal rewind, step rewind, pause, fast forward, normal forward and step forward).

### 4.2 Digital- Summary 🗲

🚟 FiTROI	FiTRONIC - FitroSway										×			
File Subject Exercise View SetuP About														
🖻 🖬 불	; 🙀 😂	Real sim	Real simulation 💦 👁 🌹 🗉 🗐 123 🗐 💈 🖉 DA 🛀 🛱 🛱 🥵 🤶							?				
		Digital	Þ	Summary										
		Graph re	port	Interval Summa	ary									
Name:	Slovak Ja	Difus ana	alysis	Attempt		F		v	Veiaht:		80			_
				Target Summa	ry	t		-						
				Driving Summa	ry									
				Frequency Ana	lysis	E							1	
Attempt	Length X	Length Y	DX/DY	velocity-mean										
#	(mm)	(mm)	(1)	(mm/s)										
1	118,9	81,9	1,5	16,1										

Provides data about the distance in the direction of the X and Y axis, the ratio of the distance in the direction of the X and Y axis as well as the average velocity of the COP during the test.

## 4.3 Digital- Interval Summary

	Sitron 🚟	liC - Fit	roSway									
ŀ	File Subject	: Exercise	View Set	uP Abou V. V		호 호, <sup>1</sup> 2, 호, :	≤. ≤: ~~ DA	\$L] \$	Pi bio	<b> </b> =	2	
ļ	Attempt No. 1		Сору	Copy All	Export xml	interval 2 s	• •		tor tor			
	Name:	Slovak Ja	in				Weigh	nt:	80		]	
	Interval	Length X (mm)	Length Y (mm)	DX/DY (1)	Velocity-mean (mm/s)							
	0-2	22,9	10,8	2,1	14,2							
	2 - 4	25,2	20,7	1,2	18,6							
	4-6	18,9	15,1	1,3	13,7							
	6-8	10,0	10,7	0,9	8,7							
	Summary:	41,3	24,4 5,8	2,1	25,2							

Provides the same parameters as Digital Summary, but in specified time intervals.

## 4.4 Digital - Attempt

Fitronic	- FitroSway						
le Subject Ex	ercise View Se	tuP About					
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Attempt No. 1	• Сору	Copy All Ex	port xml				
Name: S	lovak Jan				Weight:	80	
Time	COP X	COP Y	Velocity	COP XG	COP YG	Distance	~
(ms)	(mm)	(mm)	(mm/s)	(mm)	(mm)	(mm)	
10	-3,3	2,9	0,1	20,9	2,9	24,1	
20	-3,3	2,9	0,1	20,8	2,9	24,1	
30	-3,4	2,9	0,1	20,6	2,9	24,0	
10	-3,4	2,8	0,1	20,9	2,8	24,3	
50	-3,4	2,9	0,1	20,6	2,9	24,0	
50	-3,4	2,8	0,1	21,0	2,8	24,3	
70	-3,4	2,9	0,1	19,7	2,9	23,1	
30	-3,4	2,9	0,0	19,7	2,9	23,1	
90	-3,4	2,9	0,1	19,7	2,9	23,1	
100	-3,4	2,9	0,0	19,7	2,9	23,1	
110	-3,4	2,9	0,0	19,7	2,9	23,1	
120	-3,4	2,9	0,1	19,6	2,9	23,0	
130	-3,4	2,9	0,0	18,5	2,9	21,9	
140	-3,4	2,9	0,0	18,5	2,9	21,9	
150	-3,4	2,9	0,0	18,5	2,9	21,9	
160	-35	29	0.0	19.4	20	21.0	

Provides current values (X and Y coordinates and velocity of the COP movement) in individual time points of registration (every 10 ms).

## 4.5 Digital - Target Summary

Provides figures from the target hitting test. Values are given for individual responses as well as averages from the entire test, from left to right: order, response reaction, distance, response time and COP movement velocity.

🚟 FiTRONiC - Fit	roSway				
File Subject Exercise	View SetuP About				
🛸 🖬 🝃 📑 🎒	X V. S. V.	.}s ◆ 🔻 ź ź;	123 Z T Z Z Z M	DA 👯 🏥 🔡	8
	Copy Copy All	Export xml Dele	te		
Name: Slovak Ja	n		w	eight: 80	
				-	
No	Movement	Distance	Time	Velocity	
(#)	Direction	(m)	(ms)	(m/s)	
1	right	0.065	1150	0.057	
2	rear	0,096	800	0,120	
3	front	0,144	1250	0,115	
4	right	0,111	1250	0,088	
5	left	0,104	1050	0,099	
6	rear	0,076	850	0,090	
	left	0,077	850	0,090	
8	right	0,109	1/60	0,062	
10	left	0,038	1040	0,090	
		0,000		0,000	
Average:	mean value & SD	0,092 SD:0,024	1060 SD: 290	0,089 SD:0,019	
Ready					NUM //

# 4.6 Digital- Driving Summary <sup>≤</sup> <sup>□</sup>

🗮 FiTRONiC - FitroSway	
File Subject Exercise View SetuP About	
😂 🖬 😫 🍘 🏋 🏹 🧏 🦂 א א א א א א א א א א א א א א א א א א	?
Attempt No. 1 Copy Copy All Export xml	
Name: SlovakJan Weight: 80	
	_
Average distance: 6,2 SD: 11,3	
Average distance squared: 64,4 SD: 89,8	

Provides results of the "driving test":

Distance (average and standard deviation) of the COP from the curve. Square of the distance (average and standard deviation) of the COP from the curve.

## 4.5 Digital - Frequency Analysis

Site of the second seco	FITRONIC - FitroSway									
File Subject	t Exercise Vie	w SetuP Ab	out							
🖻 🖬 불	; 😼 🎒 🕺	🛛 🦉 N 🐉 😵	<b>?</b> ⊓ c <b>?</b> s ●	🥇 ź ź,	<sup>1</sup> 23 ≦ <sub>T</sub> ≦ <sub>D</sub>	≤ <u>1</u> ≁ DA	백 백	pro 📂	<b>1</b>	?
	Co	ру Сору А	Export xm							
Name:	Slovak Jan					Weight:	80			
Attempt	Average X	SD X	Average Y	SD Y						
(#)	(mm)	(mm)	(mm)	(mm)						
1	9	9,3	14,5	16						
2	10	5,8	9,0	12						

Provides figures (averages and standard deviations) of continuous movement segments in the direction of the X and Y axis (rapid changes in direction of the movements are characterized by shorter segments and vice versa).





The graphs show data from one trial (as specified in the upper left of the screen). The left graph shows a curve representing the COP movement in the horizontal plane (X – right-left direction, Y – front-back direction).

The right graph shows the parameters as specified for Y1 and Y2 axis in the top of the screen (position in direction of the X axis, position in direction of the Y axis, movement velocity in direction of the X axis and movement velocity in direction of the Y axis). Movement in the direction of the X axis is possible by means of clicking the arrows above the graph by left as well as right cursor. You can place the cursors in any place by clicking anywhere in the graph (left cursor by left, right by right mouse button). At movement of the cursors, the figures on the X and Y axis are being updated above the graph.

Time interval between the two cursors is displayed in the middle top. The lower part contains the average values and integrals of the parameters for the X1 and X2 axis (or YL and YR) from the time interval between two cursors. Click ZOOM do display only the interval between the two cursors in the graph.

### 4.7 Diffuse Analysis DA

Diffuse analysis allows you to calculate the average distances of consecutive position points of the COP from 1. to 10 000.

The curve showing the average distance between the consecutive points consists of two typical phases. In the first distance they increase faster (curve has a steeper slope) in the next the increase is slower.

After defining the time point separating the two parts of the curve, the system calculates parameters which characterize:

The slope of the line increase from the initial segment of the curve.

The slope of the line increase of the second segment of the curve

Theoretical shift of the line from the second segment of the curve in the direction of Y axis in time point 0.

Time point and distance of completion of rapid withdrawing of the consecutive points.





#### 5. SETUP

### 5.1 Graph Setup 💾

Specifies the graph parameters and evaluation of the static balance test. The time scale for X axis is set in the upper left corner, below it, the COP trajectory length (in points) on the left graph, duration of displaying the COP trajectory after the test (in seconds), time interval of graph display and method of COP display (in a real scale, or in a scale in which a zero point for X and Y axis is the position in the moment of starting the measurement (data collection).

Graph Setup						X
		GR	APH AXES SCALI	NG		
Time axis (s)		MIN	MAX	STEP		
10		CO	PX and Y-axes s	caling		
COD been levely	COP after Test	-50	50	20		
100	5	Y1 - axes			Y1 - axes	
1	1	-100	100	20	COP-X 💌	
Display Graj	oh (s)	¥2			¥2 auga	
From: 0 To:	10	-100	100	20		
		1	1	1	,	
C center COP						
		_	Cancel		OK	

In the right corner, the scaling of the X and Y axis of the graph is set which is displayed in the right of the screen.

In the two lower lines, the scaling of the Y1 /YL and Y2 (YR) axis is set, and the parameters which will be displayed on these axes are specified. The parameter can be modified in the evaluation routine directly on the screen above the graph.

By confirming (click OK), the settings are stored into the configuration file.

## 5.2 DA Graph Setup

DA Y-axes	Setup & (	Graph opti	ions	×
	MIN	МАХ	STEP	
r (mm)		50	5	
r2 (mm2)	0	1000	100	
x (mm)	0	50	5	
y (mm)	0	50	5	
	a: 0,0002	2999 b: 4,8	31561	
	OK		Cancel	

In the window, the graph parameters for diffuse analysis are set, the minima, maxima, and the step in displaying the average distance of consecutive points (r), or its square (r2), distance in direction of X and Y axis.

# 5.3 New Protocol

The routine is used for creating a protocol for location of stimuli in the Target hitting test. After entering the name of the protocol, choose the location of the targets (top, bottom, right, left), then add it to the protocol (click ADD). You can either change (CHANGE), or delete (DELETE) any of the stimulus, or add another one (ADD).

Click SAVE to save the protocol. Click OK to activate the created protocol in a computer's memory, without its storage.

Protocol name:	protocol 1	
No. 1 2 3 4 5 6	Location left front right rear left left	Location left front right rear Add Insert Delete Change
ОК	Save	Cancel



Serves for saving the protocol of the Target hitting test into memory.



Serves for saving the protocol of the Target hitting test to a hard disk.

6. About 🦻

Information about the program version

About FitroSway	X
Fitro Sway Version 3.1 Copyright (C) 2008-201 FITRONIC GK	I